

# Shadowing of pseudo-orbits

Pablo D. Carrasco <sup>\*1</sup>

<sup>1</sup>ICEx-UFMG, Avda. Presidente Antonio Carlos 6627, Belo Horizonte-MG, BR31270-90

March 15, 2023

## Abstract

In this note we give an effective version of the Hirsch-Pugh-Shub shadowing theorem.

## 1 Partially hyperbolic systems

We will be concerned with a generalization of the classical shadowing property for hyperbolic systems. The setting for this is in the context of partially hyperbolic diffeomorphisms, which we now define.

**Definition 1.1.** *Let  $M$  be a closed Riemannian manifold. We say that a  $C^r$  diffeomorphism  $f : M \rightarrow M$  is partially hyperbolic if there exists a continuous splitting of the tangent bundle into a Whitney sum of the form*

$$TM = E^u \oplus E^c \oplus E^s$$

where neither of the bundles  $E^s$  nor  $E^u$  are trivial, and such that

1. all bundles  $E^u, E^s, E^c$  are  $Df$ -invariant;
2. for all  $x \in M$  and for all unit vectors  $v^\sigma \in E_x^\sigma$  ( $\sigma = s, u, c$ ),
  - (a)  $\|D_x f(v^s)\| < \|D_x f(v^c)\| < \|D_x f(v^u)\|$ ;
  - (b)  $\|D_x f(v^s)\| < 1 < \|D_x f(v^u)\|$ .

**Remark 1.1.** *It is no loss of generality to assume that the Riemannian metric is such that the bundles  $E^s, E^c, E^u$  are orthogonal, and we will assume that from now on.*

The bundles  $E^s, E^u, E^c$  are the *stable*, *unstable* and *center* bundle respectively. We also define the bundles  $E^{cu} = E^c \oplus E^u$  and  $E^{cs} = E^s \oplus E^c$ , the *center stable* and *center unstable* bundles. Some important examples of partially hyperbolic diffeomorphisms are ergodic automorphisms of the torus, time-1 maps of hyperbolic flows, circle extensions over Anosov diffeomorphisms, and perturbations of those. For a discussion of these and other examples we refer to [5].

The stable manifold theorem (see [8]) implies that the bundles  $E^u$  and  $E^s$  are integrable to continuous foliations  $\mathcal{W}^u, \mathcal{W}^s$  whose leaves are of the same degree of differentiability than  $f$ . These leaves are homeomorphic to Euclidean spaces of the corresponding dimension. Nonetheless, the transversal regularity of those foliations is only Hölder in general [4]. The integrability of the center bundle  $E^c$ , on the other hand, cannot be asserted in general as the example in [7] shows (see also [3]). Establishing necessary and sufficient conditions that guarantee this property remains one of most important problems in the area.

---

<sup>\*</sup>pdcarasco@mat.ufmg.br

Some partial results in this matter can be found in [6],[2] and [1]. Let us point out also that for most known examples the center bundle is integrable.

Here however, we are interested in the properties of the foliations that integrate the bundles  $E^c, E^{cs}, E^{cu}$ . We will work then with systems satisfying the following.

**Definition 1.2.** A partially hyperbolic diffeomorphism is dynamically coherent if the bundles  $E^c, E^{cu}$  and  $E^{cs}$  are integrable to  $\mathcal{C}^{1,0}$  invariant foliations<sup>1</sup>  $\mathcal{W}^c, \mathcal{W}^{cu}, \mathcal{W}^{cs}$  and such that

$$\mathcal{W}^c = \{W^{cu} \cap W^{cs} : W^{cu} \in \mathcal{W}^{cu}, W^{cs} \in \mathcal{W}^{cs}\}.$$

As explained in [2], it follows that

1.  $\mathcal{W}^s$  sub-foliates  $\mathcal{W}^{cs}$
2.  $\mathcal{W}^u$  sub-foliates  $\mathcal{W}^{cu}$

**Notation:** for  $r > 0, x \in M, \sigma \in \{s, c, u, cs, cu\}$  denote  $W^\sigma(x, r)$  the plaque centered at  $x$  of radius  $r$  of the foliation  $W^\sigma$ .

**Local Product Structure.** Dynamical coherence implies that the system has *local product structure*, namely there exists some  $c_{lps} > 0$  such that if  $d(x, y) < c_{lps}$  and  $P_x, P_y$  denote plaques of  $\mathcal{W}^c$  centered at  $x, y$  of radius  $c_{lps}$  then  $W^s(P_x, c_{lps})$  meets  $W^u(P_y, c_{lps})$  along a plaque of  $\mathcal{W}^c$  of radius at least  $c_{lps}/2$ . In fact, local product structure is equivalent to dynamical coherence; the proof is not hard.

If the system has local product structure one can specify locally each plaque as follows. For a point  $x \in M$  we define the sets  $H_x = W^u(P_x, 2c_{lps}), V_x = W^s(P_x, 2c_{lps})$ . Given any two points  $x, y \in M$  such that  $d(x, y) < c_{lps}$  both intersections  $H_x \cap V_y$  and  $V_x \cap H_y$  consist of center plaques, and by reducing  $c_{lps}$  if necessary, there will be only one center plaque in the intersection  $H_x \cap V_y$  meeting  $W^u(x, 2c_{lps})$ , and likewise there exists only one center plaque of  $V_x \cap H_y$  intersecting  $W^s(x, 2c_{lps})$ . One sees then that the plaque through  $y$  is specified by these two points in  $W^u(x, 2c_{lps})$  and  $W^s(x, 2c_{lps})$ .

It is no loss of generality to assume that  $c_{lps}$  is less than the injectivity radius of  $\exp : TM \rightarrow M$ , and by reducing this constant even more (using that  $D_0 \exp = \text{Id}$ ), that for  $x, y \in M, d(x, y) < c_{lps}$  implies

$$d(x, y) = \inf\{\text{length}(\gamma) : \gamma : [0, 1] \rightarrow M \text{ piecewise differentiable}, \dot{\gamma} \in E^s \cup E^c \cup E^u\}.$$

Given  $x, y \in M$  such that  $d(x, y) < \delta$ , where  $0 \leq \delta \leq c_{lps}$  we define the *bracket between  $x$  and  $y$*  as

$$[x, y] = W^s(x, 2c_{lps}) \cap W^{cu}(y, 2c_{lps})$$

Since  $\exp|_{\{(x, v) \in TM : \|v\| \leq c_{lps}\}} \rightarrow M$  is nearly an isometry and since the angle between  $E^c, E^u$  and  $E^c, E^s$  is bounded away from zero, one sees that for some constant  $A > 0$  depending only on the angles we have

$$d(x, [x, y]) < A\delta \tag{1}$$

$$d(y, [x, y]) < A\delta \tag{2}$$

**Holonomy.** Let  $f : M \rightarrow M$  be a dynamically coherent partially hyperbolic diffeomorphism and fix once and for all a differentiable subbundle  $N \subset TM$  transverse to  $E^c$ , with small angle with  $E^s \oplus E^u$ . For  $0 < r \leq c_{lps}, x \in M$  denote  $D^{su}(x, r) = \exp(\{(x, v) : \|v\| < r, v \in N^{su}\})$ . Then for  $x, y$  such that  $y \in W^c(x, \frac{c_{lps}}{2})$ , the center holonomy  $H_{y,x}^c : D^{su}(x, \frac{c_{lps}}{2}) \rightarrow D^{su}(y, c_{lps})$  can be defined: for  $z \in D^{su}(x, r)$

$$H_{y,x}^c(z) = W^c(z, c_{lps}) \cap D^{su}(y, c_{lps}).$$

We will also consider  $H_{y,x}^c|_{W^s(x, \frac{c_{lps}}{2})} \rightarrow W^s(y, c_{lps})$  (if  $y \in W^{cs}(x, \frac{c_{lps}}{2})$ ) and  $H_{y,x}^c|_{W^u(x, \frac{c_{lps}}{2})} \rightarrow W^u(y, c_{lps})$  (if  $y \in W^{cu}(x, \frac{c_{lps}}{2})$ ).

The foliations  $\mathcal{W}^s, \mathcal{W}^u$  also (of course) induce related holonomy maps  $H^s, H^u$ . For the domain of  $H^s$  we use discs inside center-unstable leaves, while for  $H^u$  we use center-stable discs. We omit the discussion, which is analogous to what we wrote above.

<sup>1</sup>This means that the regularity of the leaves is  $\mathcal{C}^1$  while the transversal regularity is continuous.

## 2 Pseudo-orbits

We recall some definitions.

**Definition 2.1.** Let  $f : M \rightarrow M$  be a homeomorphism preserving a foliation  $\mathcal{F}$ .

1. A sequence  $\underline{x} = \{x_n : N_1 \leq n \leq N_2\}$  where  $N_1 \in \mathbb{Z} \cup \{-\infty\}$ ,  $N_2 \in \mathbb{Z} \cup \{\infty\}$  is called a  $\delta$ -pseudo-orbit for  $f$  if  $d(fx_n, x_{n+1}) \leq \delta$  for every  $n = N_1, \dots, N_2 - 1$ .
2. The pseudo-orbit  $\underline{y} = \{y_n : N_1 \leq n \leq N_2\}$   $\epsilon$ -shadows the pseudo-orbit  $\underline{x} = \{x_n : N_1 \leq n \leq N_2\}$  if  $d(x_n, y_n) < \epsilon$  for every  $n = N_1, \dots, N_2$ .
3. We say that the  $\delta$ -pseudo-orbit  $\underline{x}$  is subordinated to the foliation  $\mathcal{F}$  if for every  $n \in \{N_1, \dots, N_2 - 1\}$ ,  $f(x_n)$  belongs to the plaque of  $\mathcal{F}$  that is centered at  $x_{n+1}$  and has radius  $\delta$ .

Now we fix a  $f : M \rightarrow M$  a dynamically coherent partially hyperbolic diffeomorphism.

**Definition 2.2.** Let  $R > 0$  and let  $\underline{x} = (x_n : N_1 \leq n \leq N_2)$  be a pseudo-orbit. We say that  $\underline{x}$  is a  $R$ -center pseudo-orbit if it is a  $\delta$ -pseudo-orbit subordinated to  $\mathcal{W}^c$ .

The first relevant theorem involving pseudo-orbits of these notes is the following.

**Theorem A (Shadowing I).** Let  $f : M \rightarrow M$  be a dynamically coherent partially hyperbolic diffeomorphism. Then there exists a constant  $C(f) > 0$  (only depending of  $f$ ) such that for  $R$  sufficiently small, any  $R$ -pseudo-orbit can be  $C(f)R$ -shadowed by a  $C(f)R$ -center pseudo-orbit.

This result is due to Hirsch, Pugh and Shub (see theorem 7A-2 in [8]), where it is proved that given  $\epsilon > 0$  there exists  $R > 0$  such that any  $R$ -pseudo-orbit can be  $\epsilon$ -shadowed by a  $\epsilon$ -pseudo-orbit subordinated to the foliation  $\mathcal{W}^c$ . Here we make explicit the relation between  $R$  and  $\epsilon$ .

Observe that in the theorem above, if we assume that  $\underline{x}$  is close to be a center pseudo-orbit, we expect to be able to shadow it with a center pseudo-orbit  $\underline{y}$  with less error in the transverse direction. Let us formalize this notion.

**Definition 2.3.** Let  $0 < \delta \leq R$  and let  $\underline{x} = (x_n : N_1 \leq n \leq N_2)$  be a pseudo-orbit. We say that  $\underline{x}$  is a  $(R, \delta)$ -quasecenter pseudo-orbit if it is a  $R$ -pseudo-orbit and

$$d(x_{n+1}, W^s(x_{n+1}, c_{lps}) \cap W^{cu}(fx_n, R)), d(x_{n+1}, W^u(x_{n+1}, c_{lps}) \cap W^{cs}(fx_n, R)) < \delta,$$

for all  $N_1 \leq n < N_2$ .

**Remark 2.1.** The definition of quasecenter pseudo-orbit was suggested by J. Correa.

We can prove the following.

**Theorem B (Shadowing II).** Let  $f : M \rightarrow M$  be a dynamically coherent partially hyperbolic diffeomorphism, and assume that its center bundle is  $C^1$ . Then there exist constants  $R_0, C(f) > 0$  so that for each  $0 < R \leq R_0$  we can find  $0 < \delta_R < R$  and a continuous function  $D_R : (0, \delta_R] \rightarrow [1, \infty]$  verifying

1.  $D_R(\delta) \xrightarrow{\delta \rightarrow 0} 1$ .
2. Any  $(R, \delta)$ -quasecenter pseudo-orbit can be  $C(f)\delta$ -shadowed by a  $D_R(\delta)R$ -center pseudo-orbit.

One should be able to prove a more general version of the above without assuming differentiability of the center bundle, replacing this condition by Hölder continuity of the center holonomies; possibly, it'll be necessary to relinquish the precise control given above. As these are expository notes, and since several interesting systems satisfy the cited conditions (for example, regular elements in Anosov actions), I won't worry about the general case.

### 3 Proof of the Theorem A

Denote

$$\lambda^s := \max\{\|D_x f|E^s\| : x \in M\}$$

and recall the definition of  $A$  given in (1). Due the orthogonality of the bundles it follows that  $A \xrightarrow{c_{lps} \rightarrow 0} 1$ , thus by reducing  $c_{lps}$  it is no loss of generality to assume that  $r = A\lambda^s < 1$ . Let  $L = \max\{\text{Lip}(f), \text{Lip}(f^{-1})\}$  and  $0 < \eta < c_{lps}$  so that  $2\eta \left(\frac{AL}{1-r}\right)^2 < c_{lps}$ . We consider only  $0 < R < \eta$ .

First assume that we have a finite  $R$ -center pseudo-orbit  $\underline{x} = \{x_0, \dots, x_N\}$ , and define the points  $y_0, \dots, y_N$  by

- $y_0 = x_0$
- $y_n = [x_n, f(y_{n-1})]$  for  $n = 1, \dots, N$ .

Observe that  $d(x_1, y_1), d(f(y_0, y_1)) < AR$ . We want to estimate  $d(x_n, y_n)$ ; suppose then that we have proved that  $d(x_{n-1}, y_{n-1}) < A\delta(1 + r + \dots r^{n-1})$ , with  $y_{n-1} \in W^s(x_{n-1})$ . Then we get

$$\begin{aligned} d(f(y_{n-1}), x_n) &\leq d(f(y_{n-1}), f(x_{n-1})) + d(f(x_{n-1}), x_n) \\ &\leq \lambda^s d(y_{n-1}, x_{n-1}) + R \leq A\lambda^s R(1 + r + \dots r^{n-1}) + R < R(1 + r + \dots r^n), \end{aligned}$$

and hence by (1)

$$\begin{aligned} d(x_n, y_n) &= d(x_n, [x_n, f(y_{n-1})]) \leq Ad(x_n, f(y_{n-1})) < AR(1 + r + \dots r^n) < \frac{A}{1-r}R \\ d(f(y_{n-1}), y_n) &< \frac{A}{1-r}R. \end{aligned}$$

We have thus constructed a sequence  $\underline{y} = \{y_0, \dots, y_N\}$  satisfying

1.  $d(f(y_n), x_{n+1}) \leq \frac{1}{1-r}R$
2.  $d(x_n, y_n), d(f(y_n), y_{n+1}) \leq \frac{A}{1-r}R$
3.  $\underline{y}$  is subordinate to  $\mathcal{W}^{cu}$ .

It follows by dynamical coherence that if our original pseudo-orbit  $\underline{x}$  is subordinate to  $\mathcal{W}^{cs}$  then  $\underline{y}$  is subordinate to  $\mathcal{W}^c$ .

Now we apply the same argument to the  $\frac{AL}{1-r}R$ -pseudo-orbit for  $f^{-1}$ ,  $\underline{y}^{-1} = \{y_N, y_{N-1}, \dots, y_0\}$  and get another pseudo-orbit  $\underline{z}^{-1} = \{z_N, z_{N-1}, \dots, z_0\}$  with the properties

1.  $d(f^{-1}z_{n+1}, z_n) \leq \frac{A^2L}{(1-r)^2}R$ .
2.  $d(z_n, y_n) \leq \frac{A^2L}{(1-r)^2}R$
3.  $\underline{z}^{-1}$  is subordinate to  $\mathcal{W}^c$ .

Finally we end up with a  $\left(\frac{AL}{(1-r)}\right)^2 R$ -pseudo-orbit  $\underline{z} = \{z_0, \dots, z_N\}$  for  $f$  subordinate to  $\mathcal{W}^c$ . Notice that

$$d(x_n, z_n) \leq d(x_n, y_n) + d(z_n, y_n) \leq \frac{A}{1-r}R + \left(\frac{AL}{(1-r)}\right)^2 R = C(f)R.$$

We have thus proved the theorem in the case where the pseudo-orbit is finite. Now suppose that our pseudo-orbit  $\underline{x}$  is infinite (for example bi-infinite). The previous argument allows us to find for every  $N$  a  $C(f)R$ -pseudo-orbit  $\underline{z}^N$  which

$CR$ -shadows the segment  $\{x_{-N}, \dots, x_N\}$ .

Since  $M$  is compact we can find a subsequence  $\{N_k\}_k$  such that  $z_n^{N_k} \xrightarrow{n \rightarrow \infty} z_n$ . The sequence  $\underline{z} = \{z_n\}_n$  is a  $C(f)R$ -pseudo-orbit which  $C(f)R$ -shadows  $\underline{x}$ , for numbers  $R$  so that  $CR < \eta$ .

## 4 Proof of Theorem B

The argument is the same used in the proof of Theorem A, using more precise estimates. Since  $E^c$  is  $\mathcal{C}^1$ , the center holonomies are differentiable, and in particular Lipschitz continuous: for  $0 < R < \frac{c_{lps}}{2}$  there exists  $C_{hol}(R) \geq 1$  so that if  $y \in W^c(x, R)$  then

$$z, z' \in D^{su}(x, R) \Rightarrow d(H_{y,x}^c(z), H_{y,x}^c(z')) \leq C_{hol} d(z, z').$$

Similarly for  $H^c|_{\mathcal{W}^s}, H^c|_{\mathcal{W}^u}$ . Using differentiability of  $H^c$  it's not difficult to convince oneself that by taking  $x$  and  $y$  sufficiently close, and by reducing  $R$ -accordingly, we can take  $C_{hol}(R)$  as close as 1 as desired when looking at points in the same center-stable or center-unstable leaf (recall that  $E^c$  is orthogonal to  $E^s$  and  $E^u$ ). In particular one can find  $R_0 > 0$  so that  $C_{hol} := C_{hol}(R_0)$  verifies  $r := \lambda^s C_{hol} < 1$ .

On the other hand, due to continuity of the stable and unstable holonomies (and leafwise continuity of the metric in  $\mathcal{W}^{cu}, \mathcal{W}^{cs}$ ) we can guarantee that: for every  $0 < R \leq R_0$ , given  $\epsilon > 0$  there exists  $\zeta(\epsilon, R) > 0$  so that

$$\forall x, y \in M, d(x, W^{cu}(y, R)) < \zeta(\epsilon, R) \Rightarrow H_{x,y}^s(W^{cu}(y, R)) \subset W^{cu}(x, R + \epsilon).$$

Fix  $0 < R \leq R_0$  and let  $0 < \delta_R < R$  so that  $\frac{\delta_R}{1-r} < R$ .

We now proceed as before: consider first the case when  $\underline{x} = \{x_0, \dots, x_N\}$  is a  $(R, \delta)$ -quasecenter pseudo-orbit, where  $0 < \delta \leq \delta_R$ , and define the points  $y_0, \dots, y_N$  by

- $y_0 = x_0$
- $y_n = [x_n, f(y_{n-1})]$  for  $n = 1, \dots, N$ .

Note that  $d(fx_1, fy_1) < \lambda^s \delta$ . Now consider  $z_2 = [x_2, fx_1] = W^s(x_2, c_{lps}) \cap W^{cu}(fx_1, c_{lps})$ : we have  $d(fx_1, z_2) < R$  and  $d(x_2, z_2) < \delta$ . By dynamical coherence it follows that

$$y_2 = [x_2, fy_1] = H_{z_2, fx_1}^c(fy_1) \therefore d(z_2, y_2) \leq C_{hol} \lambda \delta = r \delta$$

which in turn implies

$$\begin{aligned} d(y_2, x_2) &= \delta + r \delta = \delta(1 + r) \\ d(fy_1, y_2) &\leq E(R, \delta) R \end{aligned}$$

where  $E(R, \delta)R$  is the diameter of the smallest center-unstable disk containing the stable projection of  $W^{cu}(fx_1, R)$ . As explained above,  $\lim_{\delta \rightarrow 0} E(R, \delta) = 1$ .

To argue by induction, we suppose that we have proved that

$$\begin{aligned} d(y_n, x_n) &= \delta(1 + r + \dots r^{n-1}) \\ d(fy_{n-1}, y_n) &< E(R, \frac{\delta}{1-r}) R. \end{aligned}$$

Then

$$d(x_{n+1}, y_{n+1}) \leq r d(y_n, x_n) + d(x_{n+1}, z_{n+1}) < \delta(1 + r + \dots r^n);$$

hence, if  $z_{n+1} = [fx_n, x_{n+1}]$ , by hypothesis  $z_{n+1} \in W^c(fx_n, R)$  and thus

$$d(fy_n, y_{n+1}) \leq E(R, \delta(1 + r + \dots r^{n-1})) R \leq E(R, \frac{\delta}{1-r}) R$$

Observe that  $E'(R, \delta) = E(R, \frac{\delta}{1-r})$  verifies  $\lim_{\delta \rightarrow 1} E'(R, \delta) = 1$ .

From this point on the reader shouldn't have any difficulty to conclude what is claimed in Theorem B, by following the same steps as in Theorem A.

## References

- [1] C. Bonatti and A. Wilkinson. “Transitive Partially Hyperbolic Diffeomorphisms on 3-Manifolds”. In: *Topology* 44.3 (2005), pages 475–508 (cited on page 2).
- [2] K. Burns and A. Wilkinson. “Dynamical Coherence, accessibility and center bunching”. In: *DCDS, (Pesin birthday issue)* 22 (2008), pages 89–100 (cited on page 2).
- [3] P. D. Carrasco et al. “Partial Hyperbolicity in Dimension Three”. In: *Ergodic Theory and Dynamical Systems* (2017) (cited on page 1).
- [4] B. Hasselblatt. “Regularity of the Anosov splitting II”. In: *Ergodic Theory and Dynamical Systems* 17.1 (1997), pages 169–172 (cited on page 1).
- [5] F. Rodriguez Hertz, M. Rodriguez Hertz, and R. Ures. “A Survey of Partially Hyperbolic Dynamics”. In: *Partially Hyperbolic Dynamics, Laminations and Teichmüller Flow*. Edited by Mikhail Lyubich Charles Pugh Michael Shub Giovanni Forni. Volume 51. Fields Institute Communications. 2007, pages 35–88 (cited on page 1).
- [6] F. Rodriguez Hertz, M. Rodriguez Hertz, and R. Ures. “On the Existence and Uniqueness of Weak Foliations in Dimension 3”. In: *Geometric and probabilistic structures in dynamics* 469 (2008), pages 303–316 (cited on page 2).
- [7] F. Rodriguez Hertz, M. Rodriguez Hertz, and R. Ures. “A Non-Dynamical Coherent Example in  $\mathbb{T}^3$ ”. In: *Annales de l’Institut Henri Poincaré C, Analyse non linéaire* 33.4 (2010), pages 1023–1032 (cited on page 1).
- [8] M. Hirsch, C. Pugh, and M. Shub. *Invariant Manifolds*. Volume 583. Lect. Notes in Math. Springer Verlag, 1977, pages 1–154 (cited on pages 1, 3).